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**Bruno Siciliano**  
**Paolo Dario** (Eds.)

# Experimental Robotics VIII



**Springer**

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**Gregory S. Chirikjian,Howie  
Choset,Marco Morales,Todd Murphey**



## **Experimental Robotics Viii Springer Tracts In Advanced Robotics V 8:**

**Algorithmic Foundations of Robotics VIII** Gregory S. Chirikjian, Howie Choset, Marco Morales, Todd Murphey, 2009-12-29 This book contains selected contributions to WAFR the highly competitive meeting on the algorithmic foundations of robotics They address the unique combination of questions that the design and analysis of robot algorithms inspires

**Cooperative Robots and Sensor Networks 2015** Anis Koubâa, J. Ramiro Martínez-de Dios, 2015-05-18 This book compiles some of the latest research in cooperation between robots and sensor networks Structured in twelve chapters this book addresses fundamental theoretical implementation and experimentation issues The chapters are organized into four parts namely multi robots systems data fusion and localization security and dependability and mobility

**The Synthesis of Three Dimensional Haptic Textures: Geometry, Control, and Psychophysics** Gianni Campion, 2011-05-16 The sense of touch is fundamental during the interaction between humans and their environment in virtual reality objects are created by computer simulations and they can be experienced through haptic devices In this context haptic textures are fundamental for a realistic haptic perception of virtual objects This book formalizes the specific artefacts corrupting the rendering of virtual haptic textures and offers a set of simple conditions to guide haptic researchers towards artefact free textures The conditions identified are also extremely valuable when designing psychophysical experiments and when analyzing the significance of the data collected The Synthesis of Three Dimensional Haptic Textures Geometry Control and Psychophysics examines the problem of rendering virtual haptic textures with force feedback devices The author provides an introduction to the topic of haptic textures that covers the basics of the physiology of the skin the psychophysics of roughness perception and the engineering challenges behind haptic textures rendering The book continues with the presentation of a novel mathematical framework that characterizes haptic devices texturing algorithms and their ability to generate realistic haptic textures Finally two psychophysical experiments link the perception of roughness with the parameters of the haptic rendering algorithms This book formalizes the specific artefacts corrupting the rendering of virtual haptic textures and offers a set of simple conditions to guide haptic researchers towards artefact free textures The conditions identified are also extremely valuable when designing psychophysical experiments and when analyzing the significance of the data collected

**Experimental Robotics VIII** Bruno Siciliano, Paolo Dario, 2003-01-21 This book is a collection of papers on the state of the art in experimental robotics Experimental Robotics is at the core of validating robotics research for both its systems science and theoretical foundations Because robotics experiments are carried out on physical complex machines of which its controllers are subject to uncertainty devising meaningful experiments and collecting statistically significant results pose important and unique challenges in robotics Robotics experiments serve as a unifying theme for robotics system science and algorithmic foundations These observations have led to the creation of the International Symposia on Experimental Robotics The papers in this book were presented at the 2002 International Symposium on Experimental Robotics

**Redundancy in**

**Robot Manipulators and Multi-Robot Systems** Dejan Milutinović, Jacob Rosen, 2012-10-12 The trend in the evolution of robotic systems is that the number of degrees of freedom increases This is visible both in robot manipulator design and in the shift of focus from single to multi robot systems Following the principles of evolution in nature one may infer that adding degrees of freedom to robot systems design is beneficial However since nature did not select snake like bodies for all creatures it is reasonable to expect the presence of a certain selection pressure on the number of degrees of freedom Thus understanding costs and benefits of multiple degrees of freedom especially those that create redundancy is a fundamental problem in the field of robotics This volume is mostly based on the works presented at the workshop on Redundancy in Robot Manipulators and Multi Robot Systems at the IEEE RSJ International Conference on Intelligent Robots and Systems IROS 2011 The workshop was envisioned as a dialog between researchers from two separate but obviously related fields of robotics one that deals with systems having multiple degrees of freedom including redundant robot manipulators and the other that deals with multirobot systems The volume consists of twelve chapters each representing one of the two fields

Human Haptic Perception Martin Grunwald, 2008-12-10 Haptic perception human beings active sense of touch is the most complex of human sensory systems and has taken on growing importance within varied scientific disciplines as well as in practical industrial fields This book s international team of authors presents the most comprehensive collection of writings on the subject published to date and cover the results of research as well as practical applications After an introduction to the theory and history of the field subsequent chapters are dedicated to the neuro physiological basics as well as the psychological and clinical neuro psychological aspects of haptic perception FastSLAM Michael Montemerlo, Sebastian Thrun, 2007-04-27 This monograph describes a new family of algorithms for the simultaneous localization and mapping SLAM problem in robotics called FastSLAM The FastSLAM type algorithms have enabled robots to acquire maps of unprecedented size and accuracy in a number of robot application domains and have been successfully applied in different dynamic environments including a solution to the problem of people tracking

**Gaze Interaction and Applications of Eye Tracking: Advances in Assistive Technologies** Majaranta, Päivi, 2011-10-31 Recent advances in eye tracking technology will allow for a proliferation of new applications Improvements in interactive methods using eye movement and gaze control could result in faster and more efficient human computer interfaces benefitting users with and without disabilities Gaze Interaction and Applications of Eye Tracking Advances in Assistive Technologies focuses on interactive communication and control tools based on gaze tracking including eye typing computer control and gaming with special attention to assistive technologies For researchers and practitioners interested in the applied use of gaze tracking the book offers instructions for building a basic eye tracker from off the shelf components gives practical hints on building interactive applications presents smooth and efficient interaction techniques and summarizes the results of effective research on cutting edge gaze interaction applications *Rising Stars in Human-Robot Interaction* Bilge Mutlu, Ginevra Castellano, James Everett Young, Séverin

Lemaignan, Adriana Tapus, 2022-08-11      American Book Publishing Record ,2004      **Experimental Robotics VIII** Bruno  
 Siciliano, Paolo Dario, 2014-03-12      **Proceedings 2003 IEEE/RSJ International Conference on Intelligent Robots and  
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